# Meeting 4

Date: 20 – Match – 2020

Agenda

* Status of modelling EZ10
* Maps and modelling of UWA buildings
* Map creation blockers
* Virus contingency plan

## Attendance

* Professor Thomas Bräunl
* Oluwafemi Stephen Arowosafe
* Guangming Chen
* Yunzhuo Chen
* Gerardo Cisneros Mendoza

## Glossary of terms and acronyms

CARLA - Open-source simulator for autonomous driving research.

ROS - Robot Operating System. A flexible framework for writing robot software.  
EZ10 – Easy Mile Autonomous Shuttle

## Minutes

* Craig posted the licence of RoadRunned on Microsoft Teams.
* Elevetion maps information missing to get RoadRunner maps complete, Thomas
* Craig metined to use the corect scale on Unreal Engine
* Thomas metioned to do the simple navigaton with arrows, break and accelation.
* Sthephen commented that there are 2 ways
* Steer wheel setup will need to be change from the initial one,
* Get the bus going and maps, two teams

## Attachments

No attachments included.